

PATENT ABSTRACTS OF JAPAN

(11)Publication number : 07-136173

(43)Date of publication of application : 30.05.1995

(51)Int.Cl.

A61B 17/00

A61B 1/00

A61B 1/00

A61B 17/28

B25J 7/00

(21)Application number : 05-285206

(71)Applicant : OLYMPUS OPTICAL CO LTD

(22)Date of filing : 15.11.1993

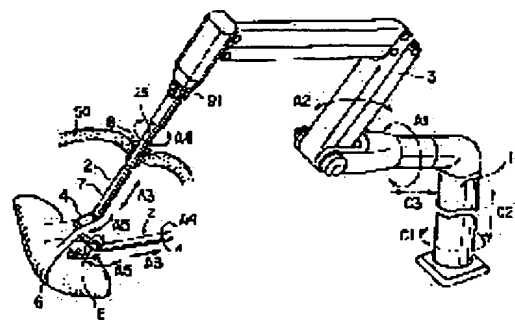
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(54) MANIPULATOR FOR OPERATION

(57)Abstract:

PURPOSE: To prevent excessive force from working on other organs than those desired in contact therewith during working by providing a sufficient freedom to accomplish an observation and a treatment in a celom.

CONSTITUTION: In this manipulator 1 for operation used to observe and/or treat a tissue in vivo being driven by a remote control, a straight inserting part 2 insertible vivo, a manipulator body 3 having a positioning means to position the inserting part 2 while linking the inserting part 2 free to advance or retract, and working parts 4 and 5 with are connected to the tip of the inserting part having a bending part free to bend to observe or treat the tissue in vivo are provided.



LEGAL STATUS

[Date of request for examination] 22.11.1999

[Date of sending the examiner's decision of rejection] 18.03.2003

[Kind of final disposal of application other than the examiner's decision of rejection or application converted registration]

[Date of final disposal for application]

[Patent number] 3476878

[Date of registration] 26.09.2003

[Number of appeal against examiner's decision of rejection] 2003-06643

[Date of requesting appeal against examiner's decision] 17.04.2003

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of rejection]

[Date of extinction of right]

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